Fundamental of ODES

-Last time:

of:IR->IR is locally Lip. if for all compact subsets DCIR, IL>O s.t.

 $\|f_{\alpha}-f_{\alpha}\| \leq F\|x-\lambda\|$ 4 xyED •It is globally Lip. if the inequality is true everywhere $\|f_{cer}-f_{cyr}\| \leq \|x-y\|$ VX,YEIR If f(t, x) is also a function of time, then f: [to,ti] XIR" ->IR" is locally Lip in X uniformly on tE[toiti] if I compact subsets OCIR $\|f_{(t,X)} - f_{(t,Y)}\| \leq L \|X - Y\| \quad \forall x, y \in D$ $\forall t \in [t_0, t_1]$ -globally Lipns 11fc+, x1- fc+, y) || & L 11.x- y 11 dx y 61Rn $\forall t \in [t_2, t_1]$

Thm : (Existence and uniqueness)

Consider ODE, X = f(t, X), $X(t_0) = X_0$ Assume Ordinary differential equation (#) Assume - fis piecewise continuous in t. - locally Lip. in X uniformly in t Elto, til on Xo Then, for all XOEIR, ESTO S.t. there exists a unique solution to (+) on the interval Ito, to + 8] - If fct,x) is globally Lip. unit in tElto,00) Then, the solution exists for all time. Remark: [Khalil Footnote 3 pp 88] -If we only care about existence, not uniqueress, then continuity of Fox) is enough.

e.g. fasz SX

Contraction mapping theorem proof: -we will use CMT to prove existence and uniqueness. - we have to write the equation as a fixed point problem. . Integrate the opE to get $X(t) = X_0 + \int_t^t f(s, X_{cs}) ds$ $\forall t \in [t_0, t_i]$ - Consider the space $\chi = C([t_0, t_i]; \mathbb{R})$ - Consider the map with $\mathbb{N} \cdot \mathbb{N}_{00}$ - norm - Consider the map it maps a continuous $\mathcal{P}: \chi \rightarrow \chi$ funct. to a continuous tunct. $(P X) (t) \triangleq X_0 + \int_t^1 f(cs, X_{cs}) ds$ \$t f [to,ti]

- The solution to the ODE is a fixed point 6F X = PXwe will use CMT to prove existence and uniqueness of solution. Conditions for CMT (I) Define a closed subset SEX (I) P(X) ES for all XES $(I) || P(x_1 - P(y_1)|| \leq P(|| X - Y||)$ where $P \in (0,1)$ to be determined start with I later $S = \{ X \in C([t_0, t_0 + \delta]; | \mathbb{R}^n) | \| X - X_0 \| \leq r \}$ (1,) Xel 5 is closed -> exercise

II need to show if XES => PXES

equivalently if ||X(t)-Xo||≤r => NPX(t)-Xo||≤r for all tE[toptotd] for all tE[toptotd]

 $PX(t) - X_0 = S_t^{\dagger} f(s, X(s)) ds$

 $= \int_{t_0}^{t} [f(c_s, \chi_{c_s}) - f(c_s, \chi_o) + f(c_s, \chi_o)] ds$

 $\implies ||PK(t) - X_0|| \leq \int_{t_0}^{t} ||f(s, X_{cs_1}) - f(s, X_0)|| + ||f(s, X_0)|| ds$

Of f is piecewise continues in t => it is bounded

 $\implies \max_{t \in [t_0, t_1]} ||f(t, X_0)|| = h < \infty$

@ 11×41-X.11 < r and f is locally Lip. =>

 $\exists L > 0 \quad \text{s.t.} \quad \|f(t_1 X dt)] - f(t_2 X_0)\| \leq L \|X dt - X_0\| \leq Lr$



So, in order to ensure PXES, we need





 $|(PX)(t) - (PY)(t)| = | \int_{t}^{t} f(s, X_{us}) - f(x, Y_{us})' ds$

 $\leq \int_{t_{-}}^{t} |f_{CS}, \chi_{LS}| - f_{CS}, Y_{LS}| ds$

Lip. t $\leq J_t L | X cs) - Y cs) ds$ $\leq I| X - Y160$ < L 11 ×- Y1100 S

 \implies $\|PX - PY\|_{00} \leq 1 \leq \|X - Y\|_{00}$ - In order to have contraction -> LS<1 =>(8<+) - Combining the two conditions for S $\delta < \min \{ \frac{1}{2}, \frac{1}{2n+h} \}$ - Then, CMT applies, Z! solution on S or on the interval [to, totb] T (BXo) (I) all trajectories Inside the ball is closed set -> S (I) starting at Xo. X (1) remains In ball if $\delta \leq \frac{r}{1rrh}$, Lis Lip. Const. for ball (III) Constraction if SS1

proof of globall existence: - why can't we conclude globall existence? we stort at Xo -> construct Desolution for [tostors] Then we take X (tot &) as the new initial condition and construct solution for [togdo, tordord] and so on ... X_2 X_1 X_0 t_0 t_0 - The issue is that to + So+ d, + Sz+ Sz+ - - - > 00 might not extend to 00 e.g. $\delta_{k} = \frac{1}{2^{k}} \Longrightarrow t_{o} + \sum_{k} \delta_{k} \leq t_{o} + 1$

- but if f is globally tip. I universal Lip. Constant L - Two conditions: SEL $S \leq \frac{r}{4r_{th}} \xrightarrow{r \to \infty} 1$ \implies we can take $S_0 = S_1 = S_2 = - = \frac{1}{L}$ => solution can be extended indefinitely. Remark: if one knows (apriori) that the Salution is bounded, then locally Lip. is enough to ensure global existence. - In other words, it no global solution, then there should be finite-time blow-up like X=x2



 \implies fox $zx^3 \Rightarrow$ fox z^2x^2 locally Lip.

⇒ local existence

But, we can argue that the Salution

is always bounded -x30 -x30

>> by remark, we have global existence

in fact, explicit form is known

 $X(t) = Sgn(X_0) \int \frac{\chi_0^2}{1+2(t-t_0)\chi_0^2}$

Example:

 \dot{X} (t) = A (t) X (t) + g(t) f (t,X)

where Acti, gct) are piecewise Cont. int matrix vetor

⇒ over any finite interval, Acts and gats i's bounded.

=> || A (t) || < a where || . || is any induced matrix norm.

 $\|f(t, x) - f(t, y)\| = \|A(t)(x, y)\|$

< 11 A (t) 11 11 X-YH

< all X-YII UXY GIRN

≥> globed Lip.

S 3! solution on [to,ti]

=> to can be arbitrary large.

- Normof matrices induced from vector

norm.

- Consider norm $\|X\|_p = \sum X_1^p + X_2^p + \cdots + X_n^p \int^p$ on $X \in ID^n$ on XEIRⁿ

- Consider a nxn mætri'x A.

- The norm of A induced from U. Hp is



By definition, we have the inequality

 $\|A X \|_{p} \leq \|A\|_{p} \| X \|_{p}$

Special cases:

VAU = max ŽIA1 maximum absolute Calumn sum $\|A\|_{\infty} = \max_{1 \le i \le n} \hat{\Sigma} \|A_{ij}\|$ max abs. now sum

 $\|A\|_2 = \int \lambda_{max} (ATA)$

maximum Singular value

- Important in equality

 $\|A\|_2 \leq fr(AA^T) = \int \sum_{ij} A_{ij}$

Frobinius_norm